

Mechanism Design for Scheduling with Uncertain Execution Time.

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• The setting

Goal of mechanism designer:

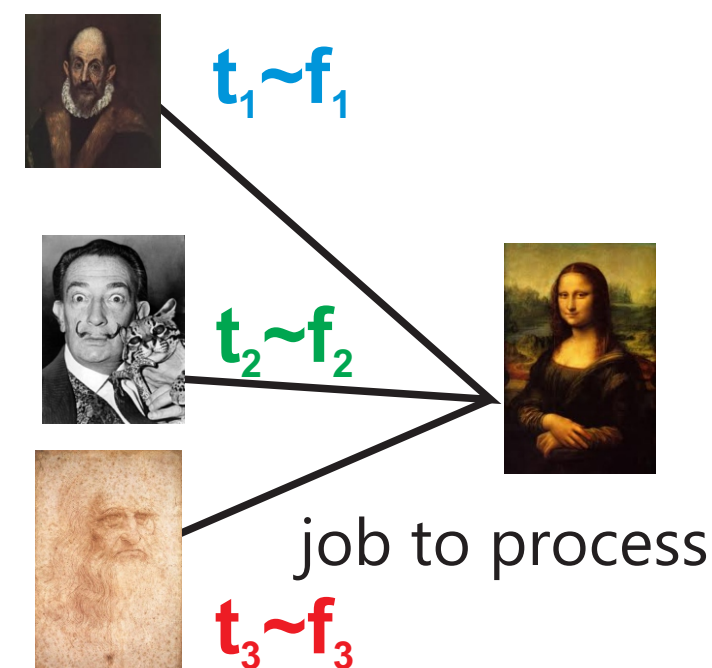
minimize E [sum of painting times]

Every day she decides which painters will draw.

Time painter i needs to finish the job \sim distribution f_i

painter i knows the distribution f_i (this is his type) from which his painting time is drawn but not his painting time t_i or the distributions of the other players f_{-i}

Players are selfish
want to maximize their utility,
which is:
 E [payment – time spent painting]



Monotone hazard rate assumption:

The probability a painter finishes the painting at time t given that he hasn't finished it until time $t-1$ is non-increasing.

We want a mechanism where the players have **no incentive to misreport their types or miscompute.**

• The efficient solution

Greedy=OPT: assign at each time step the job to the machine with maximum hazard rate, i.e. the machine most likely to finish!
To prove this we need: Monotone hazard rates assumption

OPT satisfies the **Consistency Property**:

“If we remove one player, to get OPT for the rest of the players we just need to remove the player from the schedule.”

• Expected Clarke isn't truthful

The player who is most likely to finish at the first time-step has an incentive to over-report his probability of finishing at the first step.

• Groves Realized is ex-post truthful



After completing the task we have the **realized running times**

Groves payment = $-(\text{sum of realized times of other players})$ – “sum of the **realized times** of the other players”

• Solution concept: ex-post equilibrium

Valuations are **interdependent**: a player's utility is affected by the other players' true distributions because those will affect the probability that she gets to run.

Ex-post equilibrium If the other players are telling the truth, then the best thing for me to do is to tell the truth, for **any** private information the players might have.

Dominant \subseteq Ex-post \subseteq Bayes Nash

• Vickrey Variations

h_i (types of the other players) part

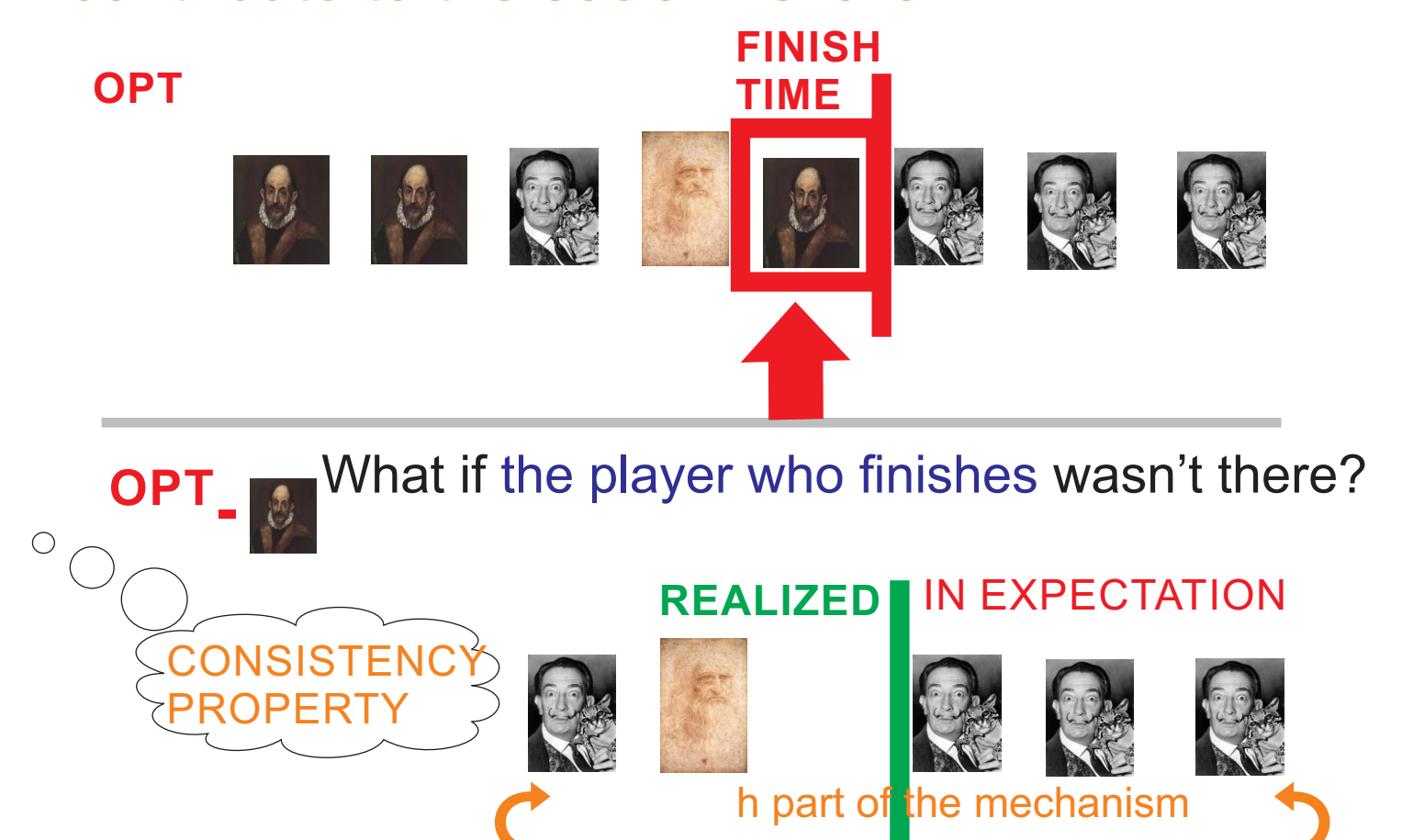
T_N := how long it takes a group N to finish the task (random variable)
 r_N := realized value of T_N

payment _{i} = $E[T_N - T_i] + E[T_{N \setminus \{i\}}]$	(CE) Clarke in Expectation
payment _{i} = $-(r_N - r_i) + 0$	Pure Realized Groves (PRG)
payment _{i} = $-(r_N - r_i) + E[T_{N \setminus \{i\}}]$	(ChE) Clarke h in Expectation
payment _{i} = $-(r_N - r_i) + (r_N - r_i) + E[T_{N \setminus \{i\}} - r_{N \setminus \{i\}} T_{N \setminus \{i\}} \geq r_{N \setminus \{i\}}]$	(ChpE) Clarke h partially in Expectation

Groves part $h_i()$

This rewriting uses the consistency property!

“How much does the player who finish contribute to the social welfare?”



• Properties of different Mechanisms

	efficient	truthful in dominant strategies	ex-post truthful	IR	no incentive to miscompute	payment 0 if fail
Clarke in Expectation (CE)	✓	✗	✗	✓	✗	✗
Pure Realized Groves (PRG)	✓	✗	✓	✗	✓	✗
Clarke h (ChE) in Expectation	✓	✗	✓	✓	✓	✗
Clarke h partially in Expectation (ChpE)	✓	✗	✓	✓	✓	✓